# **MC132x**

High Speed CMOS GigE Vision Camera

MC132x Users Manual Rev. 0.22 Camera-Firmware: <u>B2.02-V2.02-F0.71</u> Kamera ID Nr.: <u>MC1324 .. MC1327</u> Copyright © 2006 Mikrotron GmbH







# Table of contents

I	Gen		
	1.1	For customers in the U.S.A.	4
	1.2	For customers in Canada	4
	1.3	Pour utilisateurs au Canada	4
	1.4	Life Support Applications	4
	1.5	Declaration of conformity	5
	1.6	Warranty Note	6
	1.7		
2	Intro	~	
	2.1		
	2.1		
	2.3 2.4		
		Differences between the camera types         8           Using the camera         8           Hardware         9           GigE Vision® Interface         9           3.1.1 Serial interface         9           Power supply         9           Status LED         9           Getting started         10           First steps         10           Initial setup         11           Serial number and firmware revision         11           PowerUpProfile         11           Camera Profile         11           User profiles         11           Configuration         12           Commands         12           5.1.1 Table of commands         12           6.2.1 Read serial number and firmware revision         13           6.2.2 Read identifier         14           6.3.2 Read serial number and firmware revision         13           6.2.2 Read identifier         14           6.3.3 Read camera settings         14           6.3.4 Reading camera temperature         15           70-70le processing         15           6.3.1 Write user profile         15           6.3.2 Load user profile         15           6.3.3	
3	Har		
	3.1		
	3.1.1		
	3.3		
4	Gett	ting started	10
5		<u>.</u>	
	5.1		
	5.1 5.2		
	5.2 5.3		
	5.4 5.5		
		•	
6			
	6.2.1		
	6.2.2		
	6.2.3		
	6.2.4		
		· · ·	
	6.3.1		
		1	
	6.4	*	
	6.4.1		
	6.4.3		
	6.5		
	6.5.1		
	6.5.3	Address of the first pixel of a line	
	6.5.4	Address of the last pixel of a line	
	6.5.5	Tracking	
	6.6	Clock selection	
	6.6.1	Arbitrary selection of sensor and pixel clock	
	6.6.2	Table selection of clock frequencies	
	6.6.3	Image Format/Speed change	. 19
		E-manus annual	
	6.7	Exposure control	. 19
		Exposure control  Type of exposure  Frame rate with synchronous exposure	. 19 . 19

	6.7.3	Synchronous operation without shutter	21
	6.7.4	Synchronous operation with shutter	21
	6.7.5	External synchronisation with synchronous exposure	21
	6.7.6	Frame rate with asynchronous exposure	22
	6.7.7	Asynchronous exposure, shutter control by pulse width	22
	6.7.8	Asynchronous exposure, shutter control by timer	
	6.8	Firmware	
	6.8.1	Update firmware microcontroller application	
	6.8.2	Update FPGA firmware	
	6.8.3	Firmware update procedure	
	6.8.4	Reset and configuration of the internal FPGA	
		Horizontal pixelbinning	
	6.10	Vertical pixelbinning	
		Digital shading correction	
		Digital gain	
		External clock input	
		Polarity of EXP-signal	
		Test image	
		Image counter	
		ImageBLITZ® shutter release	
	6.17.1		
	6.17.2	6 1 8 8	
	6.17.3		
	6.17.4	4 ImageBLITZ® setup	29
7	MC	13xx configuration tool	30
		Basic Configuration.	
		ImageBLITZ® Configuration	
8		chanical dimensions	
O			
		Camera body MC132x	
	8.1.1	δ, · · · · · · · · · · · · · · · · · · ·	
	8.1.2	$\mathbf{c}$ ,	
	8.1.3	Dimensioned drawing, front view of MC1324/25	
	8.1.4	$\mathcal{C}'$	
	8.1.5	Dimensioned drawing, rear view of MC132x	
		Lens adjustment	
	8.2.1	Lens adaption	
	8.2.2	Adjustable lens adapter, only for camera models with C-mount flange	
	8.2.3	Lens selection for camera types with C-mount flange (see table overview of cameras)	34
9	Tec1	hnical Data	35
	9.1	Spectral response	
	9.2	Sensitive area of a pixel	
		Connector pinning	
	9.3.1	Gigabit Ethernet Connector	
	9.3.1	Circular power connector, 12-pin	
		Frequency selection	
	9.4.1	Table of clock frequency codes	
		Programming sequence, factory profile f3	
	9.6	Timing	
	9.6.1	Pixel clock	
	9.6.2	Line Valid (LVAL, DVAL)	
	9.6.3	Frame Valid (FVAL)	
	9.6.4	Exposure Signal EXP, to be input on TRIG	
	9.6.5	Synchronous exposure with external synchronisation via TRIG	45

# 1 General

#### 1.1 For customers in the U.S.A.

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense. You are cautioned that any changes or modifications not expressly approved in this manual could void your authority to operate this equipment. The shielded interface cable recommended in this manual must be used with this equipment in order to comply with the limits for a computing device pursuant to Subpart J of Part 15 of FCC Rules.

#### 1.2 For customers in Canada

This apparatus complies with the Class A limits for radio noise emissions set out in Radio Interference Regulations.

#### 1.3 Pour utilisateurs au Canada

Cet appareil est conforme aux normes Classe A pour bruits radioélectriques, spécifiées dans le Règlement sur le brouillage radioélectrique.

# 1.4 Life Support Applications

These products are not designed for use in life support appliances, devices, or systems where malfunction of these products can reasonably be expected to result in personal injury. Mikrotron customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Mikrotron for any damages resulting from such improper use or sale.

#### General

# 1.5 Declaration of conformity

Manufacturer: Mikrotron GmbH

Address: Landshuter Str. 20-22

85716 Unterschleissheim

Deutschland

Product: **camera MC1324, MC1325, MC1326, MC1327** 

The dedicated products conform to the requirements of the Council Directives 2004/108/EG for the approximation of the laws of the Member States relating to electromagnetic consistency. The following standards were consulted for the conformity testing with regard to electromagnetic consistency.

EC regulation	Description
EN 61000-6-3	Electromagnetic compatibility
EN 61000-6-1	Immunity

Unterschleissheim, August 04th. 2006

Mikrotron GmbH

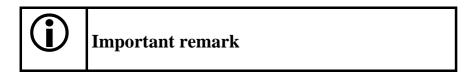
Dipl.-Ing. Bernhard Mindermann President of Mikrotron

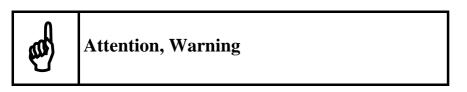
# 1.6 Warranty Note

Do not open the body of the camera. The warranty becomes void if the body is opened.

# 1.7 Remarks, Warnings

This document contains important remarks and warnings. See the corresponding symbols:





# 2 Introduction

The CMOS high speed camera MC132x is a high resolution camera with 1280 x 1024 pixel. Benefits of CMOS technology are high speed, random access to pixels with free programmability and low power.

The camera uses industry-standard C-Mount lenses. The sensor diagonal is 1,25" with square pixels measuring 12µm.

Free programmability means that the user is free to define the region of interest by size and position and the speed of data output. The frame rate can be selected between 25 fps and several thousand fps depending on resolution and video data width.

With a resolution of 1280 x 1024 pixel, 80 fps can be output via the Gigabit Ethernet Interface. Parameter sets are called "profiles" and stored in non volatile memory.

# 2.1 Top level specifications

- high resolution: 1.280 x 1.024 pixel CMOS sensor with 1300 A/D converters
- up to 1.024 gray levels
- up to 80 full frames/s up to 500 frames/s using data reduction alghorithms
- arbitrary region of interest
- high sensitivity
- 12µm square pixels
- electronic "Freeze Frame" shutter
- low blooming
- programmable via serial link
- patented ImageBLITZ® image trigger
- asynchronous trigger
- download customer specific FPGA preprocessing firmware
- small, compact housing
- wide power supply range

### 2.2 Electronic "Freeze Frame" Shutter

Preceding exposure, the contents of all light sensitive elements is cleared. When exposure terminates, accumulated charge is transferred to an analog memory associated which each pixel. It stays there until it is read out (and discharged) by the A/D conversion cycle.

As all light sensitive elements are exposed at the same time, even fast moving objects are captured without geometric distortion.

# 2.3 Differences between the camera types

The CMOS cameras are available in different versions depending on the supported features monochrome/color or Base/Full Camera Link ® interface, lens connection to C-mount or changeable lens adapter C-mount/F-mount.

Features	Data width	Color/ Mono	Max BWidth	C/F-Mount lens adaption	max. frame rate@ 1280 x 1024	Image- BLITZ®	Image pre- processing
Type	(bits)						supported
MC1324	8	M	110 Mbyte/s	С	80 fps	+	+
MC1325	8	C	110 Mbyte/s	С	80 fps	+	+
MC1326	8	M	110 Mbyte/s	F	80 fps	+	+
MC1327	8	C	110 Mbyte/s	F	80 fps	+	+

Table 2.3-1

+ ... supported

- ... not supported

# 2.4 Using the camera

There are no serviceable parts inside the camera.. The camera may not be opened, otherwise guarantee is lost.

Use dry, soft lens-cleaning tissue for cleaning lenses and, if necessary, the sensors window.

# 3 Hardware

# 3.1 GigE Vision® Interface

GigE Vision® is designed for digital cameras in machine vision applications. This interface can transfer data at a rate of 110 Mbytes/sec.

#### 3.1.1 Serial interface

# 3.2 Power supply

The camera needs a DC supply voltage between 8 ... 24 V at a power consumption of 5,0 Watt max.

See also Connector pinning.



Before applying power to the camera we strongly recommend to verify the used pins of the power connector, the polarity (+/-) of the leads and the supply voltage.

The camera may only be used with a supply voltage according to the camera specification. Connecting a lower or higher supply voltage, AC voltage, reversal polarity or using wrong pins of the power connector may damage the camera. If doing so, the warranty will expire immediately.

#### 3.3 Status LED

A dual colour LED on the camera backplane shows the operating condition of the MC132x.

LED orange... The MC132x is configuring the internal FPGA. No other activity is possible.

LED green... The MC132x is fully operational.

LED off... If LED is off, despite the camera is powered, the FPGA configuration data is re-

loaded via the serial interface and stored in internal EEPROM. No other activity

is possible.

LED red... red LED that the FPGA could not be loaded because of wrong FPGA configura-

tion data. Try to reload configuration data.

# 4 Getting started

Before starting to operate the camera, make sure that the following equipment is available:

- Camera MC132x
- C-Mount/F-Mount Lens
- Mikrotron Support CD
- Image processing system, e.g.: PC and Software



For GigE Interface the Intel MT1000 Chipset is recommended

#### Additional items:

- 1 GigE cable (CAT6 recommended)
- 1 Power supply 12VDC, 0.5A min
- 1 power cable



To specify cables see chapter **Connector pinning**.

## 4.1 First steps

- 1. Switch off the image processing system
- 2. Connect GigE cable between camera and PC.
- 3. Connect power cable.
- 4. Unscrew dust protection cover, screw in lens.
- 5. Switch on the image processing system and camera power supply

# 5 Initial setup

The MC132x is delivered with initial parameters and therefore does not need to be configured via the serial link.

#### 5.1 Serial number and firmware revision

Serial number and firmware revision is provided in MC132x non volatile memory. Use :v command (<u>Read serial number and firmware revision</u>) to read serial number and firmware revision. The serial number is also marked on the type plate of the camera.

# 5.2 PowerUpProfile

The PowerUpProfile is the contents of all camera registers to be loaded from non-volatile memory after power up.

#### 5.3 Camera Profile

The actual set of parameters is called Camera Profile. All changes of parameters by the serial link is reflected in the Camera Profile. On command the Camera Profile is saved to 8 user profiles or one PowerUpProfile. It is loaded from 8 user profiles or 8 factory profiles or the PowerUpProfile. The camera profile is volatile and must be stored to the PowerUpProfile to be reactivated on next poer up.

# **5.4** Factory profile

The factory profile can be read but not written by the user. They are factory preset to the settings described in the next chapter (user profiles).

# 5.5 User profiles

The user can store up to eight PowerUpProfiles in non volatile memory. All load or write commands exchange data between the PowerUpProfile and one of the four user profiles.

Profil-Nr.	Video data	resolution	Image
	width	/ pixel	frequency
	/Mbyte/s	_	/fps
0	48,5	100 x 100	4.852
1	58,2	240 x 240	1.011
2	62,1	640 x 480	202
3	61,6	1280 x 1024	47
4	48,5	100 x 100	4.852
5	58,2	240 x 240	1.011
6	62,1	640 x 480	202
7	61,6	1280 x 1024	47

Table 5-1

# 6 Configuration

The MC132x has 15 FPGA registers,  $r1..rf_h$ , each 10 bit wide, eight D/A registers, a1..a8, 8-bit wide, and one clock select register, 4 bit wide. The contents of all the above registers is called a profile. There is space in non volatile memory for 17 profiles: one PowerUpProfile, 8 user profiles and 8 factory profiles.

Any change of a specific register through the serial interface is immediately processed and written to the volatile part of the memory and gets lost when power goes down. A <u>command</u> must be used to store the actual setting in non volatile memory. After power-up the PowerUpProfile is loaded from the non-volatile to the volatile part of the memory.

A load or write command exchanges data between the PowerUpProfile and one of the eight user profiles. The eight factory profiles can be read but not be written by any command. All values are given in hexadecimal notation, e.g.: 0xff or 0ffh = 255.

#### 6.1 Commands

ASCII strings are used to change camera parameters. All commands start with a colon, followed by one selection character and a value in hexadecimal notation with two or three ASCII characters.

After a command has been recognized, processing is immediate, for all commands but the save type commands (:px). These need a EEPROM write time of app 1ms. An answer is provided with read type commans (:v, :w, :W) or, if the command "command acknowledge flag" is set, after processing of each command an ACK or NAK character. Processing of wrong command is stopped immediately on recognizing the error. A new command must start with a colon.

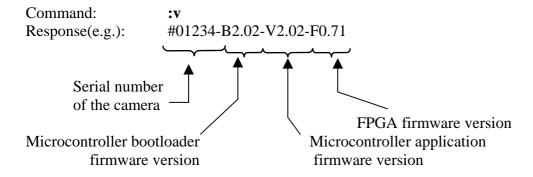
#### **6.1.1** Table of commands

Syntax	Range	Answer	Description
:a <n><xx></xx></n>	<n> = 18</n>		Set one of eight analog voltages
	$< xx > = 0ff_h$		for the sensor
:A <n></n>	<n> =</n>		En- or disable a command ac-
	"y","Y","n","N		knowledge or not acknowledge
	"		(ACK or NAK)
:b <n></n>	<n> = 04</n>		Select baud rate:
			0=9600 Bd (default setting),
			1=19.2 kBd,
			2=38.4 kBd, 3=56.8 kBd, 4=115.2
_			kBd
:C			RESET and new Initialization of the camera, new load of Pow-
			erUpProfile. Duration: some sec-
			onds
:e			Transmit & save a new FPGA
			configuration
:f <n></n>	<n> = 07</n>		Reload one of eight, factory de-
			fined and calibrated profiles to
			PowerUpProfile.
:g <n></n>	<n> = 07</n>		Reload one of eight user profiles
			to PowerUpProfile
:p <n></n>	<n> = 07</n>		Save PowerUpProfile to one of
			eight user profiles, allow app. 1ms
			save time.
:r <n></n>	$< n > = 1f_h$		Write a FPGA - register
:S	6 Byte Code		Program sensor and pixel clock
			directly.
:t <n><m></m></n>	$< n > = 007f_h$		Short setting of X- position in
	$< m > = 00ff_h$		units of 10 pixel and Y-position in units of 4 lines.
.т		+50.5	
:T :v		#12345- V1.10-F1.29	Read temperature
.v		#12345- V1.10-F1.29	Read serial number (#), microcontroller - version (V) and FPGA -
			version (F).
:V		1324000003433	Read identifier
:w		camera	Read actual PowerUpProfile, data
		profile: 44 bytes in	output in hex
		hex	output in non
:W		Camera	Read actual PowerUpProfile, data
		profile: 44 bytes in	output in ASCII
		ASCII	

# 6.2 Read camera information

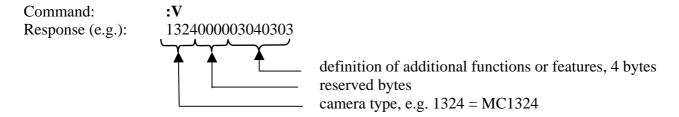
#### 6.2.1 Read serial number and firmware revision

The serial number and the firmware revision can be read with the :v command.



### 6.2.2 Read identifier

The identifier offer information about the camera type and camera functions. It consists of 8 bytes, which are delivered as 16 ascii characters.



Definition of functions or features: not yet used

#### 6.2.3 Read camera settings

The actual camera settings can be read out. The answer are the values of all camera registers.

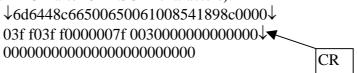
Command: :w Output as hexadecimal digits

(44 Bytes)

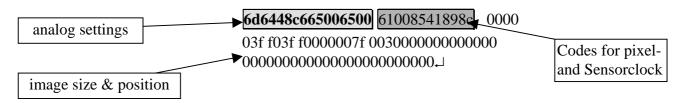
:W Output as ASCII-String

Example for ":w" (output as hex digits, 44 Databytes + CR + LF):

Example for ":W" (output as ASCII string, 91 Bytes total, 88 databytes, 1x CR preceding the databytes, 1x CR after 32 ASCII-characters and 1x CR after 64 ASCII-characters):



Assignment of data to camera parameters:



transmitted bytes:

A1 A2 A3 A4 A5 A6 A7 A8 Sa1 Sa2 Sa3 Sb1 Sb2 Sb3

R1h R11 ... R15h R15l↓

A1...A8 analog settings

Sa1 Sa2 Sa3 3 Bytes frequency codes of pixelclock (see <u>6.7</u>) Sb1 Sb2 Sb3 3 Byte frequency codes for sensorclock (see <u>6.7</u>)

R1...R15 image size & position
R1h ... high Byte Register1
R1l ... low Byte Register1

∠ ... CR+LF (0dh + 0ah)

Abb.	description	hex. Code
CR	carriage return	0d
LF	line feed	0a

#### 6.2.4 Reading camera temperature

To control the temperature inside , the camera disposes of an internal temperature sensor. The temperature inside the camera can be read out in steps of  $0.5^{\circ}$ . The value is delivered in ASCII characters signed.

Command: :T Response(e.g.): +34.0

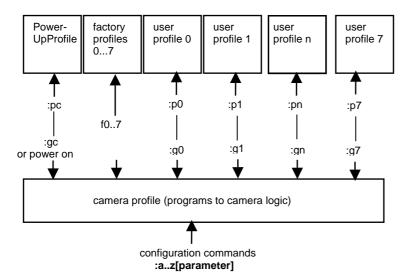
The temperature sensor is able to deliver values of  $-128^{\circ}$ C to  $+128^{\circ}$ C.



Take care that the temperature of the camera does not exceed the specified case temperature range.

# 6.3 Profile processing

All camera settings are loaded or stored as complete data blocks (= Profiles). There are 17 profiles, the Camera profile, the PowerUpProfile, eight factory profiles and eight user profiles.



### 6.3.1 Write user profile

The PowerUpProfile is transferred to one of the eight user profiles.



Issue this command only, if the PowerUpProfile was successfully tested.

#### 6.3.2 Load user profile

Load one of eight user profiles to the PowerUpProfile.

Command: :g < n > = 0 ... 7, c

#### 6.3.3 Load factory profile

The eight factory profiles can be read but not changed by the user.

Command: sf < n > 0 ... 7

# 6.4 Image quality

There are three D/A converter to influence image quality: FPN, Gain, and Black up. FPN, Gain and especially Black might be adjusted if sensor clock changes. All three parameters are stored in non-volatile memory as part of the selected profile.

#### 6.4.1 FPN

The Fixed Pattern Noise setting reduces the fixed pattern noise that is typical to CMOS sensors. This level might be changed if the sensor clock frequency is changed. For adjustment set the lens out of focus and to a medium grey level. Lower FPN until a heavy pattern appears. Then raise by a few points.

Command:  $a1 < x_1 x_0 > x_1 x_0 > : Range, typ. 55h ... 80h$ 

Response: none

#### 6.4.2 Gain

This is the threshold for the A/D converters. Its standard value is 66h for app. 1V. One step is app. 10mV. To increase the gain the value of a2 must be lowered.

Command:  $a2 < x_1 x_0 > c$   $< x_1 x_0 > c$  Range,

typ. 30h ... 80h

#### 6.4.3 Black Level

Change Black Level if sensor clock changes. Increase this parameter until grey values in no light condition (closed lens) are close to zero.

Command:  $a5 < x_1 x_0 > (x_1 x_0 > 1)$  Range, typ. 00h ...ffh

Response: none

# 6.5 Image size and position

Image size and position within the sensor is defined by four parameters:

Bit(s)	Description
r1[90]	Number of first line, 03FD <sub>h</sub>
r3[90]	Number of lines, 03FF <sub>h</sub>
r4[60]	Address/10 of the first pixel
r5[60]	Address/10 of the last pixel

Table 6.5-1

#### **6.5.1** Address of the first line

Register r1 defines the first line to be displayed.

Command:  $:\mathbf{r1} < x_2x_1x_0 >$ 

 $\langle x_2 x_1 x_0 \rangle$  ... Range 000h ...3fdh

Response: none Example: :r1100

100h = image starts at line 257



If dual column binning is activated, r1 is doubled within the camera logic.

### 6.5.2 Number of lines

Register r3 defines the number of lines to output.

Command:  $r3 < x_2x_1x_0 >$ 

 $\langle x_2 x_1 x_0 \rangle$  ... Range 000 h ...3ffh

Response: none

Example: :r3200 200h = display 513 lines



The sum of r1 and r3 must be  $\leq 0x3ff/1023$  or 0x1ff/511 if dual column binning is activated!

### 6.5.3 Address of the first pixel of a line

Register r4 defines the leftmost pixel. The value is the pixel address divided by ten.

Command:  $:\mathbf{r4} < x_2x_1x_0 >$ 

 $\langle x_2 x_1 x_0 \rangle$  ... Range 000h ...7fh

Response: none

Calculation of the value of r4:

Value of r4 = Pixel-Nr./10

# 6.5.4 Address of the last pixel of a line

Register r4 defines the rightmost pixel. The value is the pixeladress divided by ten.

Command:  $:\mathbf{r}_{5}< x_{2}x_{1}x_{0}>$ 

 $\langle x_2 x_1 x_0 \rangle$  ... Range 000h ...07fh

Response: none

Calculation of the value of r5:

Value of r5 = Pixel-Nr./10



The difference r5 - r4 must be in the range:  $0 \le r5 - r4 \le 7fh$ .

#### 6.5.5 Tracking

For rapid window movement even at slow baud rates a short command is provided..

command: :t<*n*>,<*m*>

 $\langle m \rangle = X$ -position in pixel/10,

range 00h ...07fh

 $\langle n \rangle$  = Y-position in lines / 4,

range 00h ...0ffh

Response: none

#### 6.6 Clock selection

The MC132x is equipped with a 2-channel programmable clock synthesizer. One channel controls clock frequency of the sensor (sensorclock,  $F_{sens}$ ), the other controls the frequency of the pixel clock (pixel-clock,  $F_{pix}$ ). These independent clocks allow an always optimal ratio depending on the product of (image size x image frequency) and the data rate on the output.

As the sensor outputs 10 pixel per clock a sensor clock of 6.6MHz could be chosen. Because the sensor can run up to a clock frequency of 66 MHz only 1/10 of the sensors possible speed would be used. To make use of the maximum sensor clock and maintaining the maximum data rate on the output, just 120 (1280/10 rounded to steps of 10) from the possible 1280 pixel per line can be selected.

Therefore the ratio of  $F_{sens}$  and  $F_{pix}$  depends on the selected line length:

```
F_{sens} \le (F_{pix} \bullet 1280) / (5 \bullet line length)
```

or if 100 pixel line length is chosen:

$$F_{sens} = (33 \bullet 1280) / (5 \bullet 100) = 70,4 \text{ MHz}$$

As this exceeds the maximum sensor clock frequency,  $F_{sens}$  is chosen as 66 MHz and  $F_{pix}$  as 33 MHz.

### 6.6.1 Arbitrary selection of sensor and pixel clock

Sensor and pixel clock can be set to any value, the product of: (sensor clock • line length/1280) must always be smaller (about 10%) than the qoutient: (pixel clock / 2).

```
command :S < x_0 >
```

 $\langle x_0 \rangle$  ... 6 characters, as described in chapter <u>Frequency selection</u>

#### **6.6.2** Table selection of clock frequencies

To simplify clock selection when using video data width of 2, clocks can be selected from a table with 15 entries, each entry being optimized for four regions of line length. (see table in 9.4).

Example: 240 < line length <= 640 Pixel, clock selection s9

pixelclock: 30,0 MHz sensorclock: 11,2 MHz

resulting max. datarate on the 16-Bit output: 30,0 MHz/s \* 2 Byte = 60,0 Mbyte/sec.

This is valid for a line length between 250 and 640 pixel.

command

$$:s < x_0 >$$

$$\langle x_0 \rangle$$
 ... range  $0$  ...  $f$  (hex)



Before selecting the data rate of the camera check the maximum data rate of the GigE Connection, which must be higher (or at least the same).

#### 6.6.3 Image Format/Speed change

There are several steps necessary for a change of image format:

- i. Disable sensor controller with :r6[4] = 0.
- ii. Set image size with (:r1,:r2, :r3, :r4, :r5).
- iii. If new sensor clock = old sensor clock:
  - 1. Do not set pixel clock nor sensor clock.
- iv. If new sensor clock > old sensor clock:
  - 1. Set new pixel clock (:S6....), then new sensor clock (:S4....).
- v. If new sensor clock < old sensor clock:
  - 1. Set new sensor clock (:S4....), then new pixel clock (:S6...).
- vi. Reenable sensor controller (:r6[4]=1).

# **6.7** Exposure control

Exposure control is selected with register r6[7..4] and register r2[9..0].

Bit(s)	Description
r6[74]	Type of exposure
r2[90]	Exposure time

table 6-1

#### 6.7.1 Type of exposure

The MC132x can expose the images synchronous or asynchronous. An external signal on CC1 can be used to synchronize MC132x cameras to each other or to an external event.

#### 6.7.1.1 Synchronous exposure

Synchronous exposure means that the next image is exposed, while the current image is output. This mode provides fastest frame rate while maintaining maximum exposure time as long as 1/frame rate. If an external synchronization signal is input on CC1 its frequency range can be between 30Hz and the selected free running frame rate. Use MC13xx camera configuration tool for selection.

#### 6.7.1.2 Asynchronous exposure

With asynchronous exposure, an external signal starts exposure, and the exposed image is output immediately after the exposure ends. Exposure time is defined either by an internal timer or by the width of the external EXP (CC1) signal. The time between two consecutive EXP (CC1) edges can be indefinite. Frame rate =  $1/(\exp(\cos \theta))$  time + image output time). Image output time equals the selected free running frame rate. Use MC13xx camera configuration tool for selection.

The following registers select exposure type:

Register Bits	:r6[74]	:r7[8]	:rf[0]
camera stop	xxx0	X	X
Synchronous without elec-	0001	0	0
tronic shutter			
Synchronous with electronic	0011	0	0
shutter			
Synchronous with electronic	0011	0	1
shutter and external synchro-			
nisation signal, positive edge			
Synchronous with electronic	0011	1	1
shutter and external synchro-			
nisation signal, negative edge			
Asynchronous, pulsewidth,	1011	0	0
positive edge			
Asynchronous, pulsewidth,	1011	1	0
negative edge			
Asynchronous, timer, positive	1111	0	0
edge			
Asynchronous, timer, nega-	1111	1	0
tive edge			

Table 6.7-1

#### **6.7.2** Frame rate with synchronous exposure

The frame rate with synchronous exposure is direct proportional to the selected number of lines. The time for one line is:

$$T_{zz} = 1/F_{sens} \bullet 136 \quad [sec]$$

$$T_{zz} ...time/line$$

$$F_{sens}... Sensorclock$$

Frame rate: =  $1 / \text{(time/line} \cdot \text{number of lines+1)}$  or:

 $= F_{sens} / (136 \bullet (r3[9..0] + 2))$ 

Dependencies between image size and frame rate for typical clock frequencies are given in the following table:

image size	100x100	240x240	640x480	1280x1024
Senso rclock (MHz)	66	33	13,2	6,6
Time/line [µs]	2,06	4,12	10,3	20,6
Frames/s	4.852	1.011	202	47

Table 6.7-2

#### 6.7.3 Synchronous operation without shutter

Without electronic shutter the exposure time is 1 / frame rate.

### 6.7.4 Synchronous operation with shutter

In the sensor is implemented a freeze frame shutter, which allows to reduce the exposure time in steps of one line. The minimum value of the exposure time is the duration of 2 line periods, which is determined by the value of r2 (min. 001h).

Command:  $r2 < x_2x_1x_0 >$ 

 $\langle x_2 x_1 x_0 \rangle$  ... Range 001h ...3ffh

Response: none

Exposure time T<sub>B</sub>:

$$\begin{split} Tt_B = r2 \bullet T_{ZZ} - T_{ZZ} / \, 2 \\ T_B \dots & \text{exposure time in s} \\ r2 \dots & \text{value of register 2} \\ T_{ZZ} \dots & \text{time/line} \\ T_{zz} = 1 / F_{sens} * 136 \\ Tt_{zz} \dots & \text{Time/line} \\ F_{sens} \dots & \text{sensor clock} \end{split} \tag{s}$$

Typical exposure times:

Sensor clock	Time/line	r2	r2
frequency (MHz)	(µsec)	@ 1/5.000 s	@ 1/10.000 s
66	2,06	97	49
33	4,12	49	24
13,2	10,3	19	10
6,6	20,6	10	5

Table 6.7-3

### 6.7.5 External synchronisation with synchronous exposure

MC132x cameras can be synchronized to an external signal that is input on the EXP (TRIG) signal. The strobe output signal of a MC132x "master camera" can be used for that purpose.

See timing diagram: Synchronous exposure with external synchronisation via TRIG

The cameras frame rate must be set to a frequency slightly higher than the maximum frequency of the synchronization signal. The minimum frequency should be higher than 30Hz.

Command: :rf<0/1>

<0> ... deselect external sync signal <1> ... select external sync signal

Response: none

Make sure that a sync signal is present on EXP/CC1 before this command is issued or the "trigger on CC1" button is pressed on the MC13xx camera configuration tool.

The polarity of the sync signal can be selected with the <u>Polarity of EXP-signal</u>

#### 6.7.6 Frame rate with asynchronous exposure

The frame rate with asynchronous exposure =  $\underline{\text{Frame rate with synchronous exposure}} - (1 / \text{exposure time}).$ 

#### 6.7.7 Asynchronous exposure, shutter control by pulse width

This operating mode is selected with register 6:

:**r6**[7..4] = 0xb

Exposure time depends on the width of the external EXP – signal.

#### 6.7.8 Asynchronous exposure, shutter control by timer

This operating mode is selected with register 6:

:**r6**[7..4] = 0xf

The asynchronous exposure time is dependent on :r2[9..0]. The exposure timer counts as many lines as are defined in register :r2[9..0].

Exposure time:

 $T_B = 1/F_{sens} * 136 \bullet (1+r2[9..0])$  [Sec]

 $T_B$  ... exposure time  $F_{sens}$ .. sensor clock

example: sensor clock = 66MHz

value of r2[9..0] = 6

 $T_B = 136 \bullet 6 \bullet 15 \text{ ns} = 12,2 \,\mu\text{s}$ 

#### 6.8 Firmware

The camera possesses programmable devices, which are working with some firmware packages. New cameras were programmed with all needed firmware packages and will not need any update.

For customized firmware or additional features the camera offers the possibility to update some of the firmware versions. The procedure of updating depends on the firmware package.



Do not update more than 1 firmware at the same time. In case of updating more than 1 firmware, please start with application program, then fpga program follows.

#### 6.8.1 Update firmware microcontroller application

The microcontroller works with 2 programs, the bootloader and the application program.

The bootloader is the basic program of the microcontroller, which ensures some basic functions (e.g. communication, loading application program) and cannot be changed or updated. In standard use of the camera it will never work in the bootloader program and the version cannot be read out. It's only used for updating the application program.

The application program is the active microcontroller program in the camera, which supports communication, data handling and fpga program updates.

See description of update procedure in chapter "Firmware update procedure".

#### **6.8.2** Update FPGA firmware

MC132x's logic is integrated into a FPGA (Field Programmable Gate Array), which's configuration is stored in an EEPROM. Upon power up or a command the FPGA is loaded with this configuration. Configuration data can be downloaded via the serial interface. Mikrotron may provide configuration files (\*.ibf) on request.

After download of configuration data, this data is permanently stored in EEPROM and the FPGA is configured with the new data. Besides a power cycle, the **:c** command can be used to reconfigure the FPGA with the internally stored configuration data.

See description of update procedure in chapter "Firmware update procedure".

### **6.8.3** Firmware update procedure

Before you disable the loaded firmware please ensure that you have a adequate application firmware version to load (e.g. MC132x...A202.ibf for application firmware, MC132x...F070.ibf for fpga firmware).

- (1) Start camera and test communication, e.g. with tool press "info camera" and wait for response (serial no. and firmware)
- (2) Select in menu "Write" "Write string to camera" and write command
  - for application firmware update:

:ERASEAPP <ENTER>

- for fpga firmware update:

:ERASEEPCS1 <ENTER>

which erases the program and for application firmware will restart the camera.



After this command the camera may not be able to deliver any images, load/send/store register or profile data. The status led of the camera will turn to red.

- (3) For application firmware update only:
  - The camera now starts with the bootloader program. It is displayed during start by the status led which blink one time during power up.
  - Test communication, e.g. with MC13xx in menu "Write string to camera" and command :v. Response (e.g.): B2.02
- (4) Select in menu "Write" "Write file to camera" and choose application file MC132x\*.ibf) and open it. The file transfer will start immediately. If the camera recognizes a newfirmware it will switch off the status led.



Download of \*.ibf file via serial link takes app. 1,5 - 2 min depending on the used camera. There should be no loss of power or communication during this time!

(5) Wait until file transfer is finished and the status led turns on. If the upload of the file was successful, the led will turn to green, otherwise it will be red.

(6) Verify version string by reading serial no. and firmware versions (command: :v). The new firmware version will be displayed as part of the version string. If the version is identical to the expected the camera is ready to use for capturing images.

### 6.8.4 Reset and configuration of the internal FPGA

The command :c executes a reset in the camera. The FPGA will be reconfigured and all internal registers reloaded with the last saved PowerUpProfile. The FPGA is also configured after each power up.

Command: :c
Response: none

# 6.9 Horizontal pixelbinning

Pixelbinning adds the gray values of two adjacent pixels and outputs it as one pixel with double sensitivity. In X-direction only 512 pixels are needed to cover the sensors full size.

To retain aspect ratio, every second line is discarded, if this feature is not disabled by setting Bit 8 of register 6 (:r61xx) or vertical pixelbinning is activated.

Command: :r7010 Response: none

If discarding of every other line is not disabled (:r61xx), the contents of :r1 is doubled in camera logic. To address a specific line on the sensor, the value written into :r1 has to be divided by two and :r3 must not exceed 1ffh.

#### Example:

To output 256 lines from line 128, set r1 = 63 and r3 = 255 (=0xff).

# 6.10 Vertical pixelbinning

Vertical pixelbinning adds the gray values of two superimposed pixel of a column. This doubles sensitivity and vertical field of view. To retain aspect ratio, in addition <a href="https://example.com/horizontal/binning">horizontal/binning</a> must be activated. To activate, set bit 2 in register 6.

Command example: :r6034

Response: none

### **6.11 Digital shading correction**

For the best possible image quality even at the sensors clock limit, and non uniform lighting, the MC132x can store gray levels along one line and subtract these from all lines of an image.

To setup shading correction set: :r6[1] = 0.

Then a uniform object should be used together with the desired lighting, exposure mode and time and lens. The lens should be closed so that the remaining light level along the center line of the image is as close to zero as possible, but not reaching zero.

Then set :r6[1] = 1.

The gray levels along the center line of the image are saved in volatile memory and then subtracted form all lines of the following images, as long as this bit remains set.

# 6.12 Digital gain

Out of the 10-bits sensor data either the most significant 8 bits (gain 1), or bits 8..1 (gain 2), or the least significant 8 bits (gain 4) are selected.

Command: :r700x

x = 0: gain 1 x = 4: gain 2 x = 8: gain 4

# 6.13 External clock input

MC132x frequency synthesizer can use the Camera Link® used to synchronize several MC132x to one master clock.

To activate set Bit 9 of register 7.

Command example: :r7200

response: none



If the external reference clock is different from 3.6864 MHz, the codes for the clock synthesizer have to be recalculated.

# 6.14 Polarity of EXP-signal

The polarity of the EXP-signal can be positive- or negative active. Use :r7[8] to select.

Negativ = :r7[8] = 1Positiv = :r7[8] = 0

Command example: :r7100

Response: none

# 6.15 Test image

For testing of camera logic and video data transmission, sensor data can be replaced by an internal gray scale pattern with pixel values of 0..127. Use digital gain command to see pixel values of 0..255.

Command example: **:r7040** r7[6]

Response: none

### 6.16 Image counter

If a sequence of frames is to be recorded for long time at a high frame rate, it can be useful to mark the images for later identification or check for completeness.

MC132x has a 16-Bit image counter whose count can replace the first two pixel of every image. The image counter is cleared with every low to high transition of r7[1], the camera enable bit. It is incremented by every new image.

Command example: **:r7002** r7[1]

Response: none

### **6.17 ImageBLITZ® shutter release**

ImageBLITZ can replace an external signal (e.g.: a light barrier) to release the shutter. Like a light barrier, ImageBLITZ is used to capture fast moving objects on the exact same position on the image.

Contrary to the light barrier, ImageBLITZ uses the same information as condition to release the shutter as the then exposed image.

ImageBLITZ defines one specific line or a part of the 1024 lines as trigger window. This is true even if the selected image size is less 1024 lines or outside of the selected image area.

After activation of ImageBLITZ and after issuing the EXP signal as an enable signal, the MC131x hardware checks the gray values in the trigger window at a repetition rate that is defined by the exposure time selected with bits 3..0 of r6.

If a selectable number of pixels along that trigger window exceed or fall short of a selectable threshold, one single image is exposed and output.

To adjust ImageBLITZ®, the trigger line can be superimposed to the image. Within the selected line, 10 pixel are displayed as a dotted black- and white line as long as the selected threshold is not passed.

ImageBLITZ is configured with the registers r8..rC<sub>h</sub>:

#### 6.17.1 ImageBLITZ® processing

When ImageBLITZ® is activated with  $:r7_h[0] = 1$ :

- 1. Wait for an active edge on the EXP input.
- 2. The MC13xx exposes a line, that was chosen with :rC[9..0] and is called trigger line, for an exposure time defined by :r2[9..0]. It compares the intensity of a group of 10 pixel along the selected trigger line against an adjustable threshold (:r $A_h$ [7..0], Range: 255..0).
- 3. The number of exceedings  $(:rA_h[8] = 0)$  or fall backs  $(:rA_h[8] = 1)$ , are counted, and the result is compared to a second threshold  $(:rB_h[6..0], Range: 127..0)$ .
- 4. Each time this threshold is exceeded (release condition); an "inhibit counter" (: $rD_h[9..0]$ , Range 1..255) is loaded.
- 5. The inhibit counter" :rD<sub>h</sub>[9..0] is counted down, each time the "release condition" was not reached. Once this "inhibit counter" has expired, a new image is exposed and output. After image is output, repeat at 1.

#### 6.17.2 ImageBLITZ® programming

ImageBLITZ® is programmed by registers r8..rD<sub>h</sub> and activated with r7[0].

#### 6.17.2.1 Address of trigger line

The register rC<sub>h</sub> determines the vertical position of the trigger line in the image.

command:  $\mathbf{rC_h} < x_2x_1x_0 >$ 

 $\langle x_2 x_1 x_0 \rangle$  ... range 00h ...3ffh

Response: none

Example: :rc100

100h = 256



In pixelbinning mode the value of rC is internally doubled. The value must not be higher than 1ffh/511.

### 6.17.2.2 Leftmost pixel of the trigger line

The value of register r8 / 10 is the number of the leftmost pixel in the trigger line.

Command:  $: \mathbf{r8} < x_2 x_1 x_0 >$ 

 $\langle x_2 x_1 x_0 \rangle$  ... range 000h ...07fh

Response: none

Calculation of r8:

Value of r8 = pixel number / 10

# 6.17.2.3 Rightmost pixel of the trigger line

The end of the trigger line is determined by the value of register r9.

Command:  $\mathbf{r}9 < x_2 x_1 x_0 >$ 

 $< x_2 x_1 x_0 > \dots$  range 000h ...7fh

Response: none

Calculation of r9:

Value of r9 = pixel number / 10

### 6.17.2.4 Threshold level, mark trigger line

The threshold level is set by register  $rA_h$ . The pixel values along the trigger line are compared with this value.

Command:  $\mathbf{r}\mathbf{A}_{\mathbf{h}} < x_2x_1x_0 >$ 

 $\langle x_1 x_0 \rangle$  ... range 0 ..ffh

 $\langle x_2 \rangle = 0$ : pixel gray level  $\rangle$  threshold level,

trigger line not visible

1: pixel gray level < threshold level, trigger line not visible

- 2: pixel gray level > threshold level, trigger line visible
- 3: pixel gray level < threshold level, trigger line visible

Response: none

The trigger line is displayed as dashed, black and white line. One dash has a length of 10 pixel. The trigger line is only displayed in parts of the line where the pixel fulfill the trigger requirements. Under normal operation conditions the trigger line will be visible only in parts. The number of dashes may be counted and used for the setting of register rB<sub>h</sub>.

#### 6.17.2.5 Release condition

Register rB<sub>h</sub> contains the release condition.

The release condition is determined by the number of pixels along the triggerline that fulfill the trigger requirements.

Command:  $:\mathbf{rB}_{h} < x_{\theta,\theta} >$ 

 $\langle x_{6..0} \rangle = 0$  ..7fh, number of pixel that match the trigger requirements  $\langle x_{8..7} \rangle = 0$ : correction value 0 for the X - position of output window  $\langle x_{8..7} \rangle = 1$ : correction value 4 for the X - position of output window  $\langle x_{8..7} \rangle = 2$ : correction value 8 for the X - position of output window  $\langle x_{8..7} \rangle = 3$ : correction value 12 for the X - position of output window

Response: none

#### 6.17.2.6 Release Inhibit

The Release Inhibit function is defined with :rD<sub>h</sub>. It tells ImageBLITZ how often sequentially the "release condition" must **not** be met, before an image is output.

This feature allows to trigger an object only once on the dark- to bright edge of the scene. This avoids retriggering, once the trigger condition was met and the object is still visible within the triggerline after the image has been output.

Command:  $:\mathbf{rD_h} < x_{7..0} >$ 

 $\langle x_{7..0} \rangle = 0$  ..ffh, number of fulfilled, sequentially trigger conditions

Response: none

#### 6.17.3 ImageBLITZ® registers

Register	Bit	Description			
r7	0	= 1: activate ImageBLITZ®			
r8	60	First pixel mod. 10			
r9	60	Last pixel mod. 10			
$rA_h$	70	Exposure threshold			
	8	1: bright object triggers			
		0: dark object triggers			
	9	1: make triggerline visible			
$rB_h$	60	Number of exceedings or fall backs, release con-			
		dition,			
	87	X – tracking correction			
	9	X – tracking enable.			
$rC_h$	90	Address of triggerline			
$rD_h$	70	exposure limitation, number of exposures without			
		exposure condition until an image is captured			

Table 6.17-1

Registers r1..r7 are programmed according to image size and position and for <u>Asynchronous operation</u>, <u>timer</u>.

Register	Bit	Description
r1, r3r5		Image size and position
r2	90	Async operation, timer
r6	74	Ofh

Table 6.17-2

#### 6.17.4 ImageBLITZ® setup

The MC131x is configured for <u>asynchronous operation with timer</u>, registers r8, r9 and r $C_h$  are loaded for the desired position of the trigger line. Register r $B_h$  is loaded with 0, register r $A_h$  with 201 $_h$ , so that the trigger line is visible.



If the image is zoomed down for display by an application program, every other line may be omitted and the trigger line may then disappear.

ImageBLITZ® is enabled with Register r7 Bit1=1.

Now position the trigger line with the registers r8, r9 and rC<sub>h</sub> across the object that is used for the shutter release..

Clear Bit 8 in Register  $rA_h$  if a bright objects releases the shutter, set  $rA_h[8]$  if dark objects release the shutter. While the trigger line is placed across the object, raise threshold with  $rA_h[7..0]$  until as many dashes from the trigger line disappear as are loaded in Register  $rB_h$  [6..0]. This is called the release condition.

If it is expected that the release condition is met more than once for a single object, load  $rB_h$  [9..7] with a number of exposed lines that will not met the release condition before exposing one image.

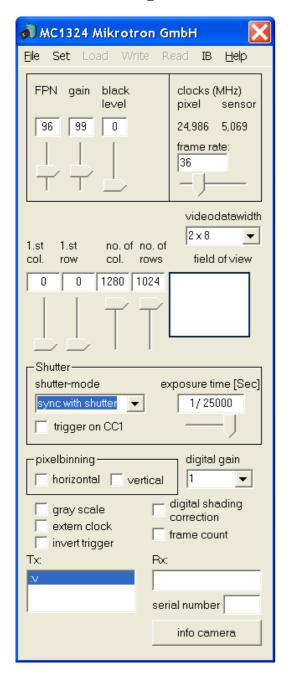
# 7 MC13xx configuration tool

The MC13xx configuration tool must be installed on a Windows PC. (Win9x, WinNT, Win2K, WinXP) by means of the setup software. See also <a href="https://www.mikrotron.de">www.mikrotron.de</a> to download the latest version.

This software provides an almost self explaining user interface to modify any camera parameter. The description of the parameters follows the marked chapters in this user manual.

To use this tool with the camera MC13xx the serial interface is integrated in the Camera Link® interface. You do not need any other additional cable.

# 7.1 Basic Configuration



**File**: Save or read settings to or from file. **Set:** Select com port. If Inspecta-4D and the correct cable is used, the MC13xx can be written to but not being read from.

Load, Write, Read: Profile processing

FPN, Gain, black level:

Clocks, frame rate:
Clock selection
Adjusting Image
Adjusting Image
Type of exposure

Frame count (6.17), gray scale (6.16), invert trigger extern clock (6.14), digital gain pixelbinning....(6.10)

### Info camera:

Read serial number and firmware version

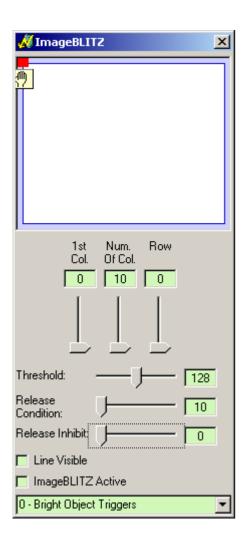
Tx:

Display control strings

Rx:

Display response

# 7.2 ImageBLITZ® Configuration



 $\mathbf{1}^{st}$  Col, Num Of Col., Row ( Position of TriggerLine ): r8, r9 and rC

Threshold:

rΑ

**Release Condition:** 

rΒ

**Release Inhibit:** 

rD

Line Visible:

rA Bit 8

**ImageBLITZ Active:** 

r7 Bit 0

**Bright Object Triggers:** 

rA Bit 9

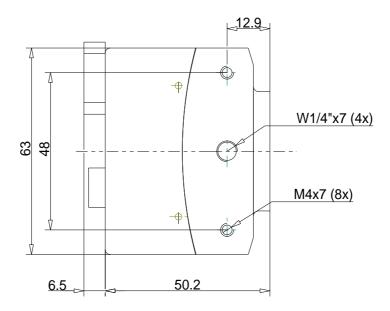
# 8 Mechanical dimensions

# 8.1 Camera body MC132x

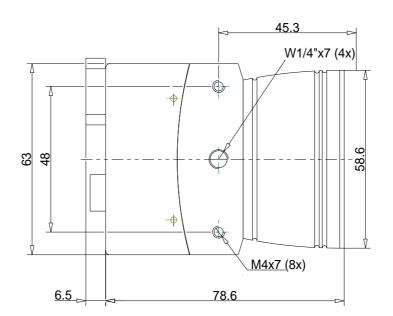
The camera body has (without lens) has very compact. To fasten the camera there are two mounting holes M4x7mm and one tripod connection on each side available.

### 8.1.1 Dimensioned drawing, side view of MC1324/25

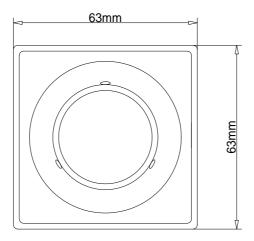
all dimensions im mm



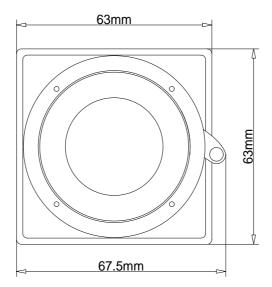
### 8.1.2 Dimensioned drawing, side view of MC1326/27



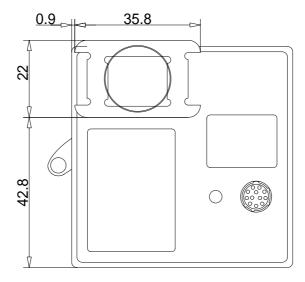
# 8.1.3 Dimensioned drawing, front view of MC1324/25



# 8.1.4 Dimensioned drawing, front view of MC1326/27



#### 8.1.5 Dimensioned drawing, rear view of MC132x



# 8.2 Lens adjustment

#### 8.2.1 Lens adaption

In dependence of the camera model the MC132x camera are prepared for either C-mount or F-mount connection (see table overview of cameras).

Camera types with F-mount adaption may be converted to C-mount adaption by exchanging the lens mount flange of the camera, which is attached with 4 screws. The C-mount lens flange is not scope of delivery of the F-mount camera types and is offered separately.

### 8.2.2 Adjustable lens adapter, only for camera models with C-mount flange

For fine adjustment of the focal length a lens adapter with an adjustment range of  $\pm$  1 mm is provided. Use the three screws nearby the sensor window to fasten the lens adapter after a proper adjustment together with the chosen lens.

#### 8.2.3 Lens selection for camera types with C-mount flange (see table overview of cameras)

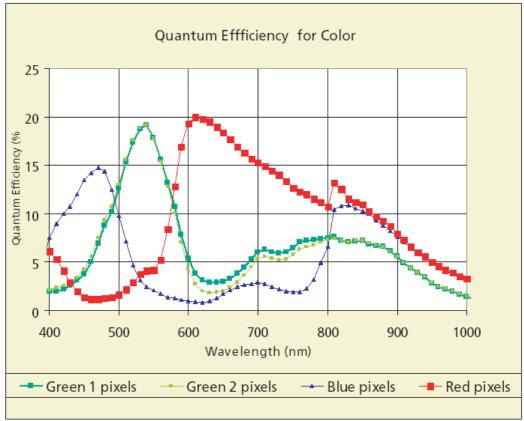
Due to the size of the sensor use C-Mount lenses with the largest possible optical diameter or an adapter for lenses like F-Mount, especially for lenses with a focal length < 25mm..

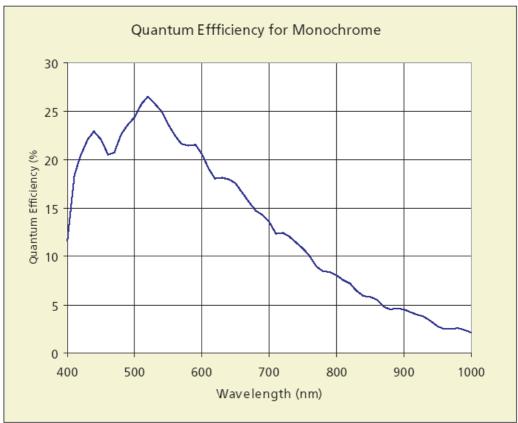
# 9 Technical Data

MC1324 MC1326	Monochrome
MC1325 MC1327	Bayer Filter
Number of pixel	1280 x 1024
Pixel size	12 x 12 μm
Active area	15,36 (H) x 12,29 (V) mm
Fill factor	40%
Sensitivity at 550 nm @ Vref	1600LSB/lux-sec
= 1V (a2 = 66h)	
Spectral response	400800nm
Shutter	Electronic "Freeze Frame" Shutter
Trigger	Asynchronous shutter, shutter time
	selectable with internal timer or by
	pulse width of trigger signal
Internal Dynamic	59 dB
Power supply	8 24 V
Power consumption max.	5 W
Thermal resistance typ.	0.17°/W
Serial data link	9,6 – 115 KBd, 8 bits, 1 stop bit, no
	parity
Digital video	GigE Vision® Interface
	Pleora GigE IPort Interface
Case temperature	+550°C
Shock & vibration	70g, 7grms
Dimensions	63 x 64,7 x 56,27 mm
(WxHxD)	
Case temperature	+5 +50° C
Weight	ca. 300 g
Lens mount	
MC1324/25	C-Mount
MC1326/27	F-Mount

Table 8.2-1

# 9.1 Spectral response



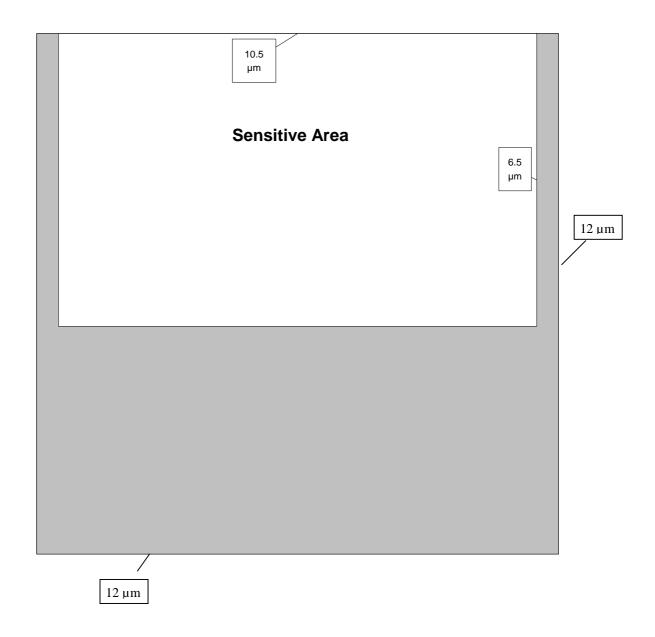


# 9.2 Sensitive area of a pixel

Pixel size:  $12 \times 12 \mu m$ 

Fill factor: 40 %

Sensitive area:  $10.5 \times 6.5 \mu m$ 



# 9.3 Connector pinning

# 9.3.1 Gigabit Ethernet Connector

## 9.3.2 Circular power connector, 12-pin



pin	signal
1	GND
2	VCC
3	STROBE_GND
4	STROBE
5	TRIG_GND
6	TRIG

pin	signal
7	
8	
9	
10	
11	VCC
12	GND

Table 9.3-1

Manufacturer: Hirose

Order no.: HR10A-10R-12P



Before applying power to the camera we strongly recommend to verify the used pins of the power connector, the polarity (+/-) of the leads and the supply voltage.

The camera may only be used with a supply voltage according to the camera specification. Connecting a lower or higher supply voltage, AC voltage, reversal polarity or using wrong pins of the power connector may damage the camera. If doing so, the warranty will expire immediately.

# 9.4 Frequency selection

Depending on the selected line length and the datarate of the GigE interface the frequency selection table can provide an optimal ratio of sensor /pixel clock. The pixel clock is only dependent on the selected step and not on the linelength.

The sensor clock is dependent on both the selected step, the line length and the data width. The tables show the selectable frequencies and the correponding codes to program the synthesizer accordingly.

### 9.4.1 Table of clock frequency codes

For free programming of the clock frequencies of pixel and sensor clock the following table can be used. All codes in the table show the code for sensor clock. The code for pixel clock is the same but starts with "6".

Example: Adjustment 1 MHz
Command for sensor clock: :S41bb0b
Command for pixel clock: :S61bb0b



Pixel and sensor clock must be adjusted in dependence of the used camera mode as described in chapter frequency selection. Undefined settings may lead to functional faults or can damage the camera.

Frequer	ncy / MHz	Code	Frequen	cv / MHz	Code	Frequen	cy / MHz	Code
Wanted	Real	0000	Wanted	Real	0040	Wanted	Real	0000
1.0	1.001	41bb0b	24.5	24.488	416905	48.0	47.923	409081
1.5	1.497	409301	25.0	24.986	41dd07	48.5	48.538	413084
2.0	2.002	41ba8b	25.5	25.498	41408a	49.0	48.976	416885
2.5	2.501	412685	26.0	26.010	41f090	49.5	49.503	416c85
3.0	2.995	409281	26.5	26.496	41c08e	50.0	49.971	41dc87
3.5	3.502	408e03	27.0	27.034	404c81	50.5	50.475	41580b
4.0	4.005	41ba0b	27.5	27.506	41788b	51.0	50.995	41400a
4.5	4.501	41f20b	28.0	28.017	408c83	51.5	51.610	404801
5.0	5.003	412605	28.5	28.508	41c48d	52.0	52.019	41f010
5.5	5.483	41d208	29.0	29.000	41cc8d	52.5	52.477	41d80f
6.0	5.990	409201	29.5	29.491	405481	53.0	52.992	41c00e
6.5	6.502	41f190	30.0	29.983	41dc8d	53.5	53.453	406802
7.0	7.004	408d83	30.5	30.497	416089	54.0	54.067	404c01
7.5	7.495	41dd8d	31.0	31.027	41888a	54.5	54.445	41740b
8.0	8.010	41b98b	31.5	31.502	416c89	55.0	55.012	41780b
8.5	8.499	414187	32.0	32.043	41b88b	55.5	55.513	41f40f
9.0	9.003	41f18b	32.5	32.507	417889	56.0	56.033	408c03
9.5	9.492	419188	33.0	32.914	41e88c	56.5	56.525	405001
10.0	10.006	412585	33.5	33.513	418489	57.0	57.016	41c40d
10.5	10.506	40d983	34.0	33.997	414087	57.5	57.508	409003
11.0	10.967	41d188	34.5	34.518	419089	58.0	57.999	41cc0d
11.5	11.520	40bd82	35.0	35.021	408c82	58.5	58.491	41d00d
12.0	11.981	409181	35.5	35.482	412886	59.0	58.982	405401
12.5	12.493	41dd87	36.0	36.013	41f08b	59.5	59.509	41b80c
13.0	13.005	41f110	36.5	36.495	418088	60.0	59.965	41dc0d
13.5	13.517	404d01	37.0	36.864	406c81	60.5	60.457	409803
14.0	14.008	408d03	37.5	37.478	40e884	61.0	60.993	416009
14.5	14.500	41cd0d	38.0	37.970	419088	61.5	61.440	405801
15.0	14.991	41dd0d	38.5	38.502	416c87	62.0	62.054	41880a
15.5	15.514	41890a	39.0	39.014	41f08a	62.5	62.423	41f00d
16.0	16.022	41b90b	39.5	39.497	412085	63.0	63.004	416c09
16.5	16.457	41e90c	40.0	40.024	412485	63.5	63.520	41b40b
17.0	16.998	414107	40.5	40.550	407881	64.0	64.087	41b80b
17.5	17.510	408d02	41.0	41.011	415886	64.5	64.512	408002
18.0	18.007	41f10b	41.5	41.472	40a882	65.0	65.015	417809
18.5	18.432	406d01	42.0	42.025	40d883	65.5	65.536	413407
19.0	18.985	419108	42.5	42.561	41f089	66.0	65.829	41e80c
19.5	19.507	41f10a	43.0	43.008	408081	66.5	66.355	406001
20.0	20.012	412505	43.5	43.500	40e083	67.0	67.025	418409
20.5	20.506	415906	44.0	43.868	41d088	67.5	67.489	41d00b
21.0	21.012	40d903	44.5	44.605	41d888	68.0	67.994	414007
21.5	21.504	408101	45.0	44.974	40e883	68.5	68.462	40f805
22.0	21.934	41d108	45.5	45.466	408881	69.0	69.036	419009
22.5	22.487	40e903	46.0	46.080	40bc82	69.5	69.515	40fc05
23.0	23.040	40bd02	46.5	46.541	418886	70.0	70.042	408c02
23.5	23.501	40c102	47.0	47.002	40c082			
24.0	23.962	409101	47.5	47.514	41c487			

### 9.4.1.1 Respective codes for the clock synthesizer

Each frequency pair corresponds to two hexadecimal codes that are used to program the synthesizer. These are also obtained on a read Camera Profile (:w) command.

Codes	Pixel co- des in MHz	Sensor codes (MHz) for: 10 < Line- length <= 100	Sensor codes (MHz) for: 100 < Line length <=	Sensor codes (MHz) for: 240 < Line length <=	Sensor codes (MHz) for: 640 < Line length <=
Step \		Pixel	240 Pixel	640 Pixel	1280 Pixel
0	612505	406d01	407182	416a85	416705
1	612505	416905	407181	40ee05	41be8b
2	612505	414088	41f988	41de09	407a81
3	612505	406c81	407102	416a05	416685
4	612505	41f489	41f10c	407182	405201
5	61fd09	416885	407101	40ed85	413207
6	616905	41f00f	416906	41f98b	410a05
7	61748b	414008	41f908	41dd89	407a01
8	61f08e	41e80c	41e890	41d188	40e203
9	61dc8d	40f405	40f487	411984	41da08
a	617489		407082	416985	416605
b	610085		407c82	40c105	41898c
c	61b489		41f08c	407102	405181
d	61f489		407081	40ed05	413187
e	60c005		41f888	41dd09	41d589
f	617409		407002	416905	416585

Table 9.4-1

There is a 3-byte code for each frequency. The code for the sensor clock is set to sb1...3 of a <u>returned</u> PowerUpProfile (command :w).

The code of the pixel frequency corresponds to sa1...3.

Example: return of frequency codes

On command: w following answer was returned:

61dc8d... Sa1...3, pixel clock (see code of table 20)

61dc8d = step 9, equivalent to 30,0 MHz

41da08... Sb1...3, sensor clock

according to table 20, mode 3

41da08= step9, equivalent to 5,6 MHz

07f.. Line length 1280 pixel

# 9.5 Programming sequence, factory profile f3

Example: resolution: 1.280 x 1.024 pixel

frame rate: 48 fps

pixel clock: 35,3 MHz sensor clock: 6,65 MHz shutter: full frame, exposure time: 21 ms

Strings: :a16d

:a277

:a34a :a4c8

:a5xx xx... may be any value 00h ... ffh

:a600

:a76a

:a81c

:r6000

:r1000

:r23ff :r33ff

:r4000

:r507f

:r7000 :r6030

:r8000

:r9000

:ra000

:rb000

:rc000

:rd000

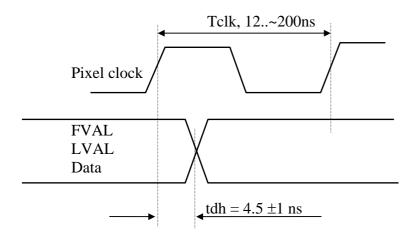
:re000

:rf000

:sb

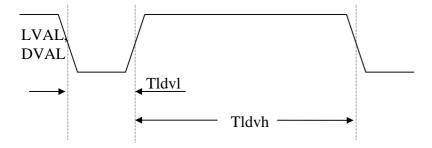
# 9.6 Timing

### 9.6.1 Pixel clock



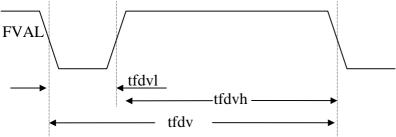
The above illustration shows hold time of video data, LVAL and FVAL signal to rising edge of pixel clock.

### 9.6.2 Line Valid (LVAL, DVAL)



LVAL and DVAL are connected internally in the camera. The timing for the LVAL / DVAL signal shown in multiples of the pixel clock depend on the ratio of sensor/pixel clock, on selected line length, and on video data width. Tldvh is always the same for a specific setting of the above parameters, Tldvl my vary by one clock from line to line. The LVAL / DVAL signal is also output while FVAL is inactive.

### 9.6.3 Frame Valid (FVAL)



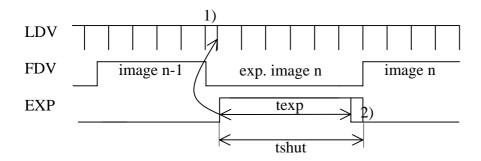
The rising edge of FVAL marks that line, that is programmed in Register r1.

Tfdvh is equal to the value programmed in Register r3 multiplied with <u>time/line</u>. Tfdvl in <u>synchronous</u> mode is equal to one <u>time/line</u>.

### 9.6.4 Exposure Signal EXP, to be input on TRIG

The EXP signal is positive active if register 7, Bit 8 = 0, negative active if register 7, Bit 8 = 1. EXP Signal may not be asserted while the previous image is output (FDV active)

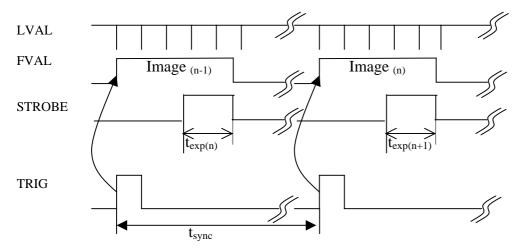
The sensors exposure starts and the <u>strobe output</u> activates (texp, (1) three sensor clocks after the active edge of the EXP signal (tshut), and ends up to 135 sensor clocks after deactivation (2).



- 1) The active edge of the EXP signal clears the horizontal counter.
- 2) End of exposure time is synchronised with the internal horizontal counter.

EXP is also used as enable signal for ImageBLITZ shutter release.

# 9.6.5 Synchronous exposure with external synchronisation via TRIG



 $t_{exp}$ : Exposure time selectable with register  $\underline{:r2}$ 

 $t_{sync}$ : The synchronisation frequency must be smaller than the framerate to which the MC13xx is set and greater 30Hz.